

Recognition of Group Activities using Wearable Sensors

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In-network GAR using Wearable Sensors

■ What is GAR?

- Why is it important?
- How can it be done?
- What is the correct approach?

■ System for GAR

- Sensor nodes
- Mobile phones
- In-network processing

■ Experiment in GAR

- Different modes evaluated
- Context abstraction levels
- Evaluated in terms of power consumption and recognition

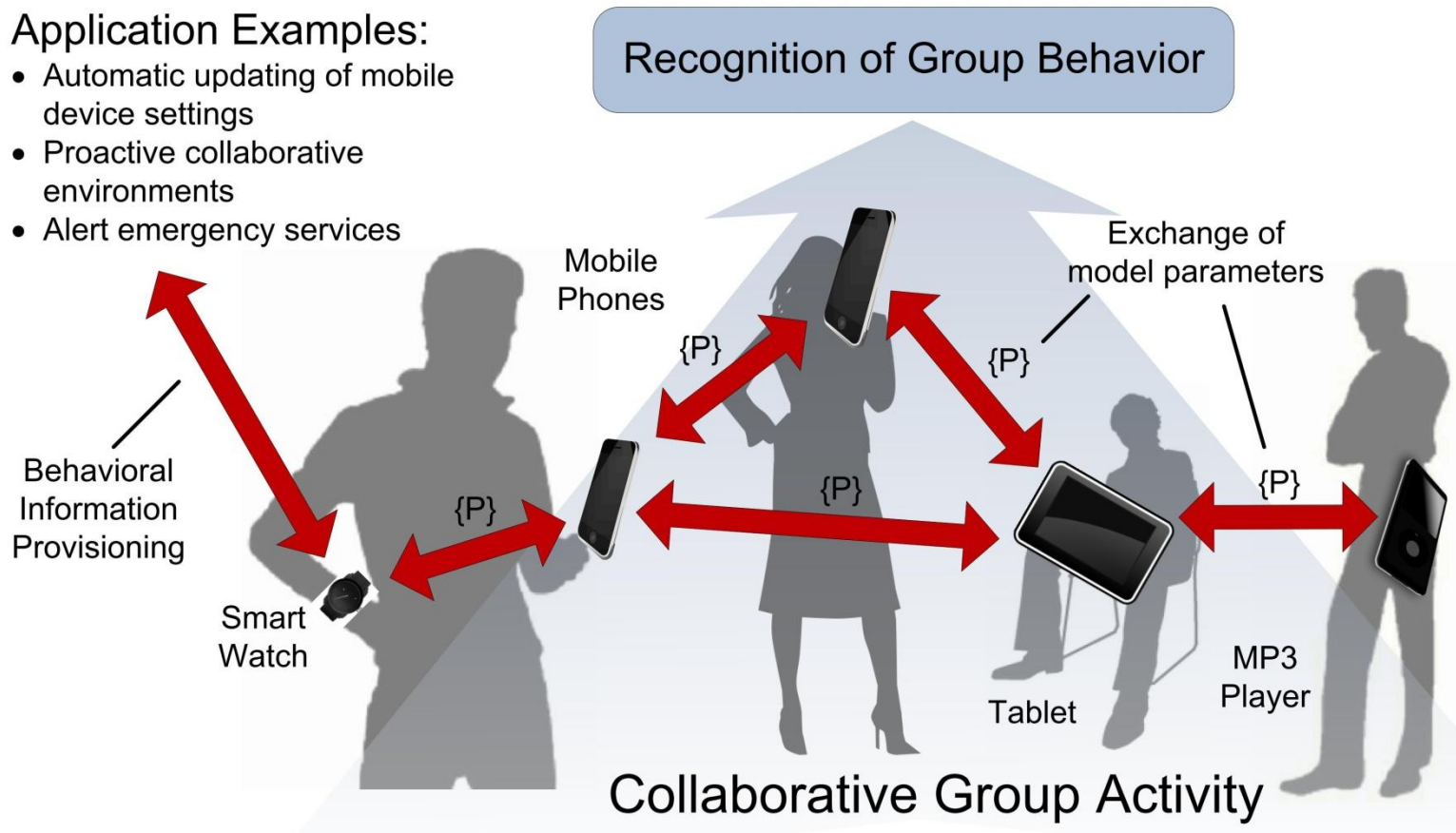
■ Results

- Features optimal abstraction level
- Using HAR as input for GAR creates problems
- Clustering promising

GAR using Mobile P2P Devices

Application Examples:

- Automatic updating of mobile device settings
- Proactive collaborative environments
- Alert emergency services



■ Devices collaborate to recognize group activity using embedded sensors

How to Approach GAR?

- Group (swarm) behavior studied in the natural kingdom: ants, fish, birds, bees, etc.
- Swarm behavior is emergent behavior resulting from behavior of individuals and interactions between them [Reynolds 1987]
- HAR shown effective for recognizing user activities, interactions
- GAR therefore based on HAR methods



What is Group Activity Recognition?



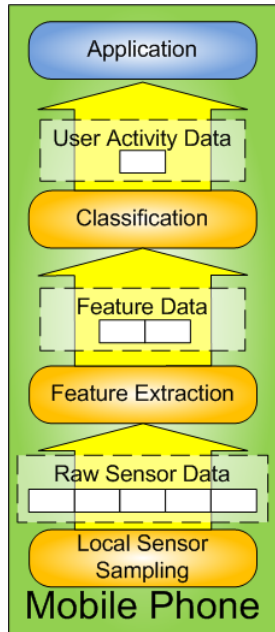
Bao & Intille 2004

- Observing key points on the body allows activities of the person as a whole to be inferred (HAR)
- In the same way, observing behavior of individuals allows us to infer activities of the group
- The group can be observed as an entity in and of itself. (GAR)



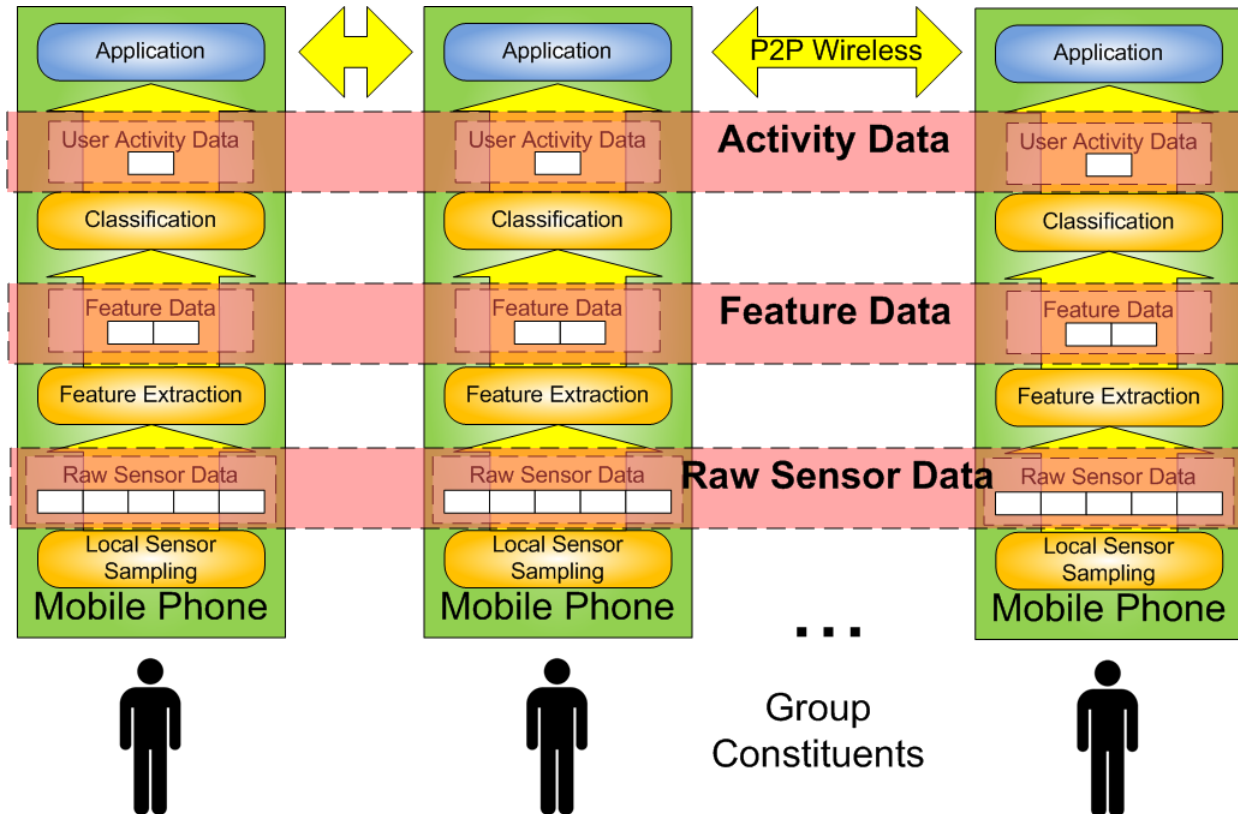
flickr: bade_md

Human Activity Recognition (HAR) using Machine Learning



- HAR using mobile sensing devices is an established field.
- Sensor sampling yields discrete measurements of continuous signals
- Windowing allows signal features to be extracted
- Machine learning matches patterns in features to activity labels
- So how do we apply this to **groups of individuals?**

Group Activity Recognition (GAR)



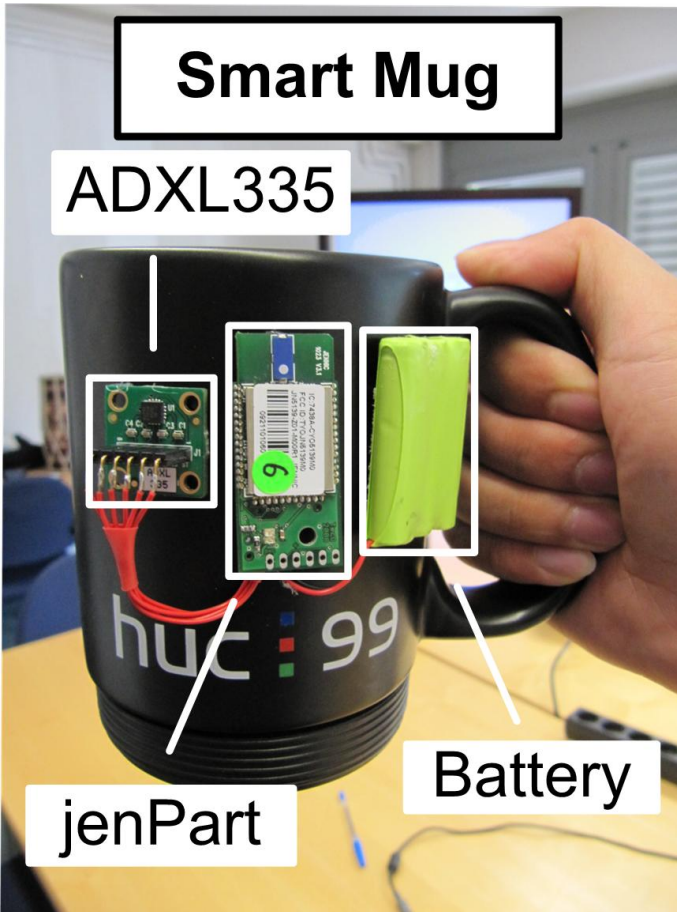
- Single-user data must be fused
- Low abstraction
 - high costs
 - high accuracy
- High abstraction
 - Lower costs
 - but accuracy?
- Where is the tradeoff?

Experiment Hardware: Wireless Sensing

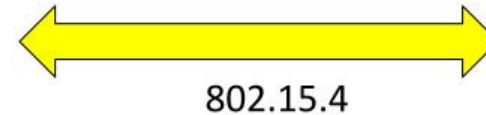
- Open-source, open-hardware sensor node project: www.jennisense.teco.edu
- ContikiOS ported to the Jennic wireless microcontroller from NXP
- Sensing
 - ADXL335 3D acceleration sensor
 - Sampled at 33 Hz
 - (Current version: 3D Acc./Gyro/Compass, light, temp, pressure, infrared distance, time-of-flight)
- Feature extraction
 - Window size of 0.5s w/ 50% overlap
 - Mean and variance only
- Single-user activity recognition
 - Supervised
 - kNN (k=10, no weighting)
 - DT (C4.5)
 - nB (no kernel estimation, single Gaussian)
 - Unsupervised
 - K-means clustering, hard, top 1
 - Uses subtractive clustering for cluster identification



P2P Architecture: Smart-Mugs and Neo



Coffee Cup/ jenPart WSN



Mobile Phone



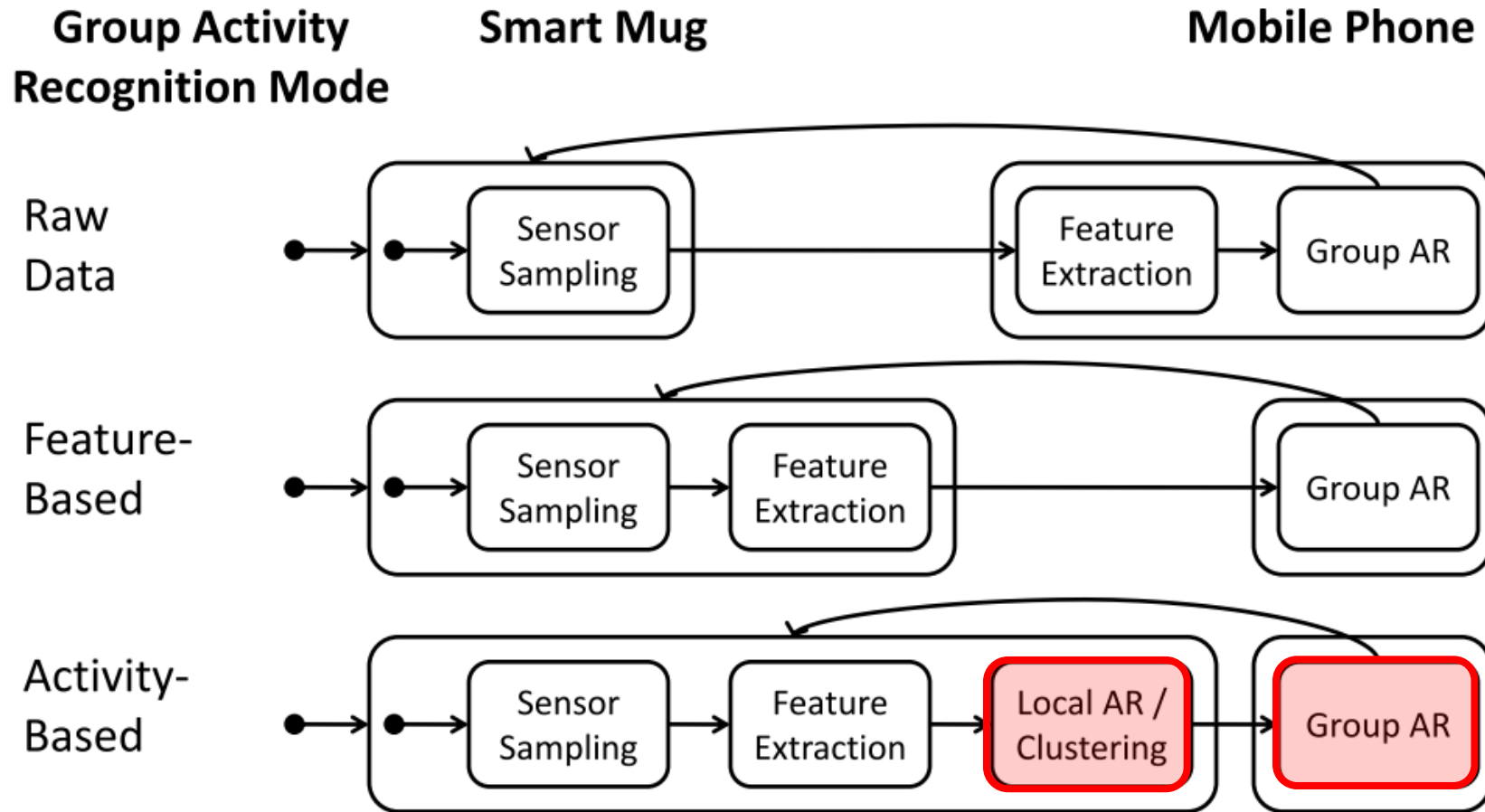
System:

- jenPart sensor node
 - ConTiki OS
- ### Tasks:
- Sensor sampling
 - Local feature extraction
 - Local activity recognition

System:

- Neo Freerunner
 - Debian Linux
- ### Tasks:
- Global multi-user group activity recognition
 - Global and local training
 - Visualization
 - Administration

System operational modes

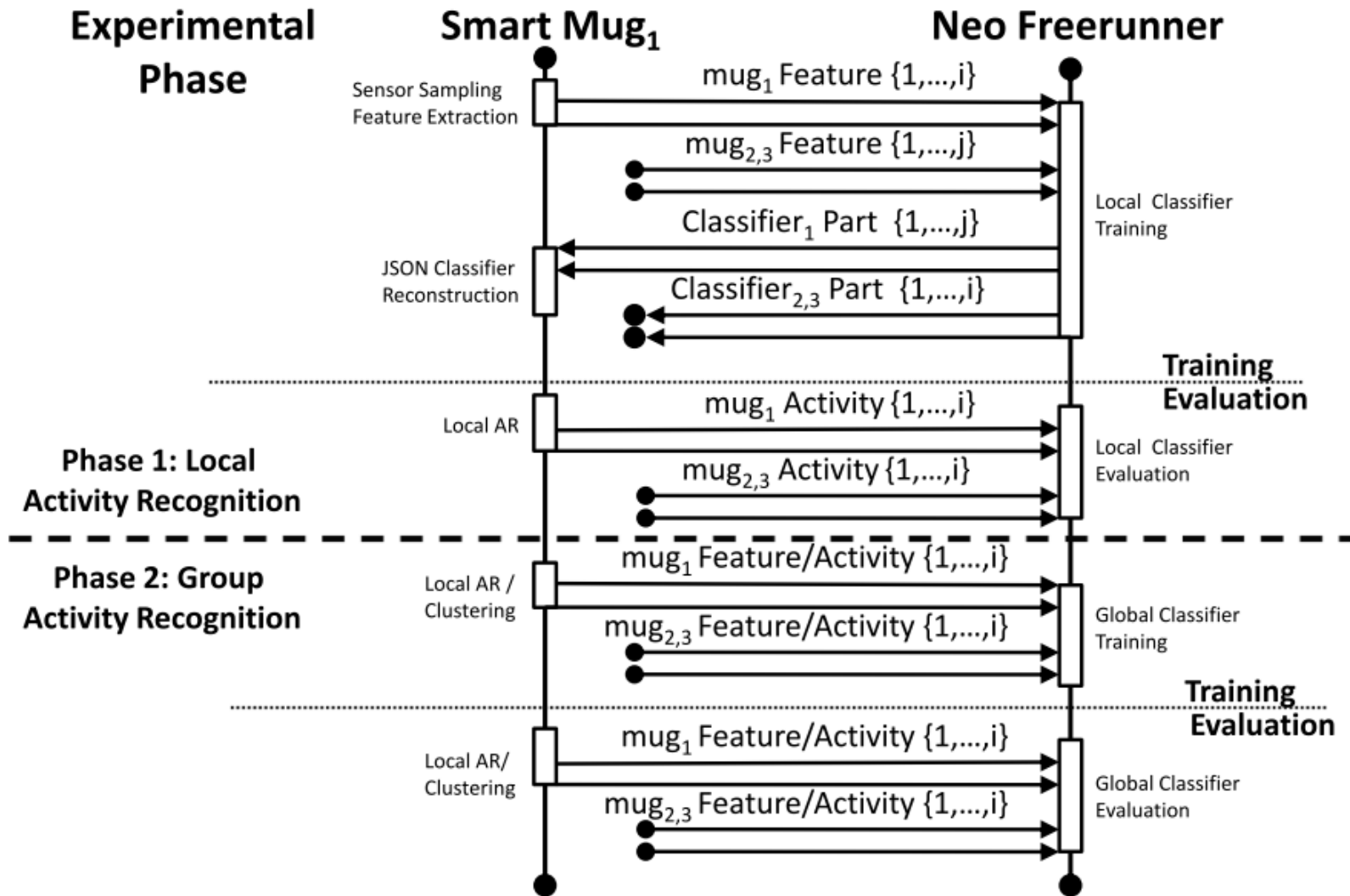


■ Doubly-labeling problem

Experiment

- Evaluate **GAR rates and power consumption** using different data abstraction levels
 - Raw sensor data
 - Sensor signal features
 - Local activities
- Raw sensor data and feature based GAR accuracies **identical (feature selection)**
- Using local activities = doubly labeling
 - Separate local and global training phases
 - Local clustering (unsupervised)
- Group activities:
 - **Meeting, Presentation, Coffee break**
- Single-user activities:
 - **Mug on table, holding in hand, gesticulating, drinking**
- 3 subjects, 45 mins, 22,700 vectors

Experiment



a) Local Activities (Averaged Over Nodes)

Data Basis	DT		kNN		nB	
	Acc.	F-meas.	Acc.	F-meas.	Acc.	F-meas.
Features	0.958	0.958	0.954	0.955	0.941	0.943

- In total 9 classifiers, 3 per node
- Values averaged over nodes
- **High results** - indicates simple classification problem
- Little variance over nodes and classifiers

Global GAR Results

Data Basis	b) Global Activities					
	DT		kNN		nB	
	Acc.	F-meas.	Acc.	F-meas.	Acc.	F-meas.
Features	0.962	0.962	0.894	0.898	0.565	0.593
Clusters	0.762	0.764	0.597	0.605	0.491	0.494
Activities	0.507	0.524	0.424	0.484	0.491	0.505

- Feature-based recognition provides **decent results** – **information is there!**
 - But (very) **naïve Bayes fails** – multiple clusters
- Using classified activities produces **low GAR rates**
 - Data analysis: users could not reproduce own behavior – min/max, variance
- Clustering produces **promising** results!
 - Hard, top-1 clustering not optimal for kNN, nB
 - Soft clustering approaches should improve on this.

Power Consumption

Mode	Data Volume (B/s)	Neo Freerunner	Smart Mug	E_{Tx} (mJ)
		Avg(P) (W)	Avg(P) (mW)	
Raw Data	404.25	1.771	24.574	1.012
Features	107.25	1.723	24.233	0.909
Classes/Clusters	12.375	1.700	23.140	0.605

- Significant reductions in transmitted data volume
- Small reductions in total device power consumption
 - Due to scenario, low sample rate, small number of features and sensors, etc.
- Better indicator is how much energy is spent on communication
 - Still doesn't quit scale with volume
 - Due to packet overheard/scenario paramters

Summary

- HAR can be used to recognize group activities
- Abstracting to features yields **96%** recognition, saves **10%** transmission energy
- Abstracting to local activities saves **33%** more energy, but creates labeling issues
 - Users cannot reproduce behavior under different conditions (**50%** acc. using activities)
 - Clustering promising (**76%** with room for improvement)
- Conditions for GAR are different than HAR
 - More distinct clusters due to multi-user (nB results)
- Future work
 - Explore other labeling approaches
 - Soft probabilistic clustering
 - Distribute GAR classification as well

That's All

- Thank You!
- Questions?